

AN400 Rev E – Application Note CAN Bus Protocol for PE3 Series ECUs Release Date 11/28/18

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Relevant Hardware: All PE3 controllers with installed CAN Bus This document defines the CAN based parameters that the PE3 is broadcasting for the firmware listed above.	Firmware/Software Version:	PE3 V3.04.55 and higher		
parameters that the PE3 is broadcasting for	Relevant Hardware:	All PE3 controllers with installed CAN Bus		
The PE3 ECU contains a 120 ohm termination resistor.	Additional Notes:	parameters that the PE3 is broadcasting for the firmware listed above. The PE3 ECU contains a 120 ohm		

CAN Bus Details

- 250 kbps Rate
- Broadcast parameters are based on SAE J1939 standard
- All 2 byte data is stored [LowByte, HighByte] Num = HighByte*256 + LowByte
- Conversion from 2 bytes to signed int is per the following: Num = HighByte*256+LowByte if (Num>32767) then Num = Num - 65536 endif

CAN ID (hex)	Name	Rate (ms)	Start Position	Length	Name	Units	Resolution per bit	Range	Туре
0CFFF048	PE1	50	1-2	2 bytes	Rpm	rpm	1	0 to 30000	unsigned int
			3-4	2 bytes	TPS	%	0.1	0 to 100	signed int
			5-6	2 bytes	Fuel Open Time	ms	0.01	0 to 30	signed int
			7-8	2 bytes	Ignition Angle	deg	0.1	-20 to 100	signed int
0CFFF148	PE2	50	1-2	2 bytes	Barometer	kpa	0.01	0-300	signed int
			3-4	2 bytes	MAP	kpa	0.01	0-300	signed int
			5-6	2 bytes	Lambda	lambda	0.01	0-10	signed int
0CFFF248	PE3	100	1-2	2 bytes	Analog Input #1	volts	0.001	0 to 5	signed int
			3-4	2 bytes	Analog Input #2	volts	0.001	0 to 5	signed int
			5-6	2 bytes	Analog Input #3	volts	0.001	0 to 5	signed int
			7-8	2 bytes	Analog Input #4	volts	0.001	0 to 5	signed int
0CFFF348	PE4	100	1-2	2 bytes	Analog Input #5	volts	0.001	0 to 5	signed int
			3-4	2 bytes	Analog Input #6	volts	0.001	0 to 5	signed int
			5-6	2 bytes	Analog Input #7	volts	0.001	0 to 5	signed int
		Ì	7-8	2 bytes	Analog Input #8	volts	0.001	0 to 22	signed int
		Ì							
0CFFF448	PE5	100	1-2	2 bytes	Frequency 1	hz	0.2	0 to 6000	signed int
			3-4	2 bytes	Frequency 2	hz	0.2	0 to 6000	signed int
			5-6	2 bytes	Frequency 3	hz	0.2	0 to 6000	signed int
			7-8	2 bytes	Frequency 4	hz	0.2	0 to 6000	signed int
0CFFF548	PE6	1000	1-2	2 bytes	Battery Volt	volts	0.01	0 to 22	signed int
			3-4	2 bytes	Air Temp	F	0.1	-1000 to 1000	signed int
			5-6	2 bytes	Coolant Temp	F	0.1	-1000 to 1000	signed int
				, , , , , ,					
0CFFF648	PE7	1000	1-2	2 bytes	Analog Input #5 - Thermistor	F	0.1	-1000 to 1000	signed int
			3-4	2 bytes	Analog Input #7 - Thermistor	F	0.1	-1000 to 1000	signed int
			5	1 byte	Version Major		1	0-255	unsigned char
			6	1 byte	Version Minor		1	0-255	unsigned char
			7	1 byte	Version Build		1	0-255	unsigned char
		İ	8	1 byte	Version Com?		1	0-255	unsigned char



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CAN ID (hex)	Name	Rate (ms)	Start Position	Length	Name	Units	Resolution per bit	Range	Туре
0CFFF748	PE8	100	1-2	2 bytes	RPM Rate	rpm/sec	1	-10,000 to 10,000	signed int
			3-4	2 bytes	TPS Rate	%/sec	1	-3,000 to 3,000	signed int
			5-6	2 bytes	MAP Rate	psi/sec or kpa/sec	1	-3,000 to 3,000	signed int
			7-8	2 bytes	MAF Load Rate	g/rev/sec	0.1	-300 to 300	signed int
0CFFF848	PE9	100	1-2	2 bytes	Lambda #1 Measured	lambda	0.001	0 to 10	signed int
			3-4	2 bytes	Lambda #2 Measured	lambda	0.001	0 to 10	signed int
			5-6	2 bytes	Target Lambda	lambda	0.001	0 to 2.5	signed int
0CFFF948	PE10	100	1	1 byte	PWM Duty Cycle #1	%	0.5	0 to 100	unsigned char
			2	1 byte	PWM Duty Cycle #2	%	0.5	0 to 100	unsigned char
			3	1 byte	PWM Duty Cycle #3	%	0.5	0 to 100	unsigned char
			4	1 byte	PWM Duty Cycle #4	%	0.5	0 to 100	unsigned char
			5	1 byte	PWM Duty Cycle #5	%	0.5	0 to 100	unsigned char
			6	1 byte	PWM Duty Cycle #6	%	0.5	0 to 100	unsigned char
			7	1 byte	PWM Duty Cycle #7	%	0.5	0 to 100	unsigned char
			8	1 byte	PWM Duty Cycle #8	%	0.5	0 to 100	unsigned char
0CFFFA48	PE11	100	1-2	2 bytes	Percent Slip	%	0.1	-3000 to 3000	signed int
			3-4	2 bytes	Driven Wheel Rate of Change	ft/sec/sec	0.1	-3000 to 3000	signed int
			5-6	2 bytes	Desired Value	%	0.1	-3000 to 3000	signed int
0CFFFB48	PE12	100	1-2	2 bytes	Driven Avg Wheel Speed	mph	0.1	0 to 3000	unsigned int
			3-4	2 bytes	Non-Driven Avg Wheel Speed	mph	0.1	0 to 3000	unsigned int
			5-6	2 bytes	Ignition Compensation	deg	0.1	0 to 100	signed int
			7-8	2 bytes	Ignition Cut Percent	%	1	0 to 100	signed int
0CFFFC48	PE13	100	1-2	2 bytes	Driven Wheel Speed #1	ft/sec	0.1	0 to 3000	unsigned int
			3-4	2 bytes	Driven Wheel Speed #2	ft/sec	0.1	0 to 3000	unsigned int
			5-6	2 bytes	Non-Driven Wheel Speed #1	ft/sec	0.1	0 to 3000	unsigned int
			7-8	2 bytes	Non-Driven Wheel Speed #2	ft/sec	0.1	0 to 3000	unsigned int
0CFFFD48	PE14	100	1-2	2 bytes	Fuel Comp - Accel	%	0.1	0 to 500	signed int
			3-4	2 bytes	Fuel Comp - Starting	%	0.1	0 to 500	signed int
	\bot		5-6	2 bytes	Fuel Comp - Air Temp	%	0.1	0 to 500	signed int
	\vdash		7-8	2 bytes	Fuel Comp - Coolant Temp	%	0.1	0 to 500	signed int
0CFFFE48	155.5					0.4			
	PE15	100	1-2	2 bytes	Fuel Comp - Barometer	%	0.1	0 to 500	signed int
	+		3-4	2 bytes	Fuel Comp - MAP	%	0.1	0 to 500	signed int
	+		5-6	2 bytes	-				
	+		7-8	2 bytes	-				
0CFFD048	DE4C	100	1.2	O budo -	Ignition Comp. Air T	doa	0.4	20 to 20	olemad ict
UCFFDU48	PE16	100	1-2	2 bytes	Ignition Comp - Air Temp	deg	0.1	-20 to 20	signed int
	+		3-4	2 bytes	Ignition Comp - Coolant Temp	deg	0.1	-20 to 20	signed int
	+ -		5-6	2 bytes	-				
			7-8	2 bytes	=				